

- Complexity analysis shows whether one algorithm is more efficient than another.
- This analysis must be independent of the physical resources used (processor, memory access time).

Complexity \equiv number of steps required to solve the problem for an input of a given size.

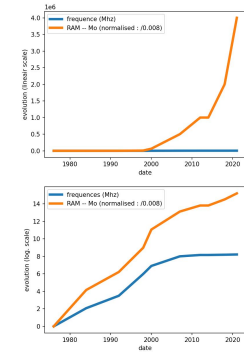
What's the point of complexity ?

- Plan the resources required for an algorithm
- What are the critical resources ?
the time, the memory, (the bandwidth of a communication)

- Complexity will depend on the machine model. Generally
 - random access memory (RAM)
 - a single processor

If this model changes, so does the complexity, since you may have to take into account communication times between processors and/or the time it takes to access information in memory.

1976	1 Mhz	8 Ko	1 core
1984	8 Mhz	512 Ko	1 core
1992	33 Mhz	4 Mo	1 core
1998	400 Mhz	64 Mo	1 core
2000	1 Ghz	512 Mo	1 core
2007	3 Ghz	4 Go	1/2 cores
2012	3.5 Ghz	8 Go	1/2/4 cores
2014	3.5 Ghz	8 Go	2/4/8 cores
2018	3.6 Ghz	16 Go	8 cores
2021	3.7 Ghz	32 Go	10 cores



Insertion sort execution time depends on the input :

- on the number of elements to be sorted
- on the nature of the array :
 - if the elements are already sorted, very quickly
the shifting is no longer necessary, and the # of comparisons is very low.
 - if sorted in reverse : much longer

- In general, execution time increases with input size.
execution time = $f(\text{input size})$
- input *size*
 - for an array : number of elements
 - for a graph : (number of vertices, number of arcs) ...
- To estimate execution time :
 - execution time for each elementary instruction

Example : Tri_insertion

1	def Tri_insertion (array):	cost	no. of passes
2	n = len(array)	c ₂	1
3	for j in range(n):	c ₃	n - 1
4	key = array[j]	c ₄	n - 1
5	i=j-1	c ₅	n - 1
6	while (i>=0) and (A[i]>key):	c ₆	$\Sigma(j - 1)$
7	A[i+1] = A[i]	c ₇	$\Sigma(j - 1)$
8	i = i - 1	c ₈	$\Sigma(j - 1)$
9	A[i+1] = key	c ₉	n - 1
10	return(array)	c ₁₀	1

The overall execution time is then given by the formula :

$$t = c_1(n - 1) + c_2(n - 1) + \dots$$

Remarks :

- If the array is already sorted : complexity **linear**.
This is the most favorable case.
- If the array is sorted in reverse : exact complexity calculable.
 - time proportional to the square of n .
 - The algorithm is said to be **quadratic**.

As execution time depends $\left\{ \begin{array}{l} \text{on the size of the input} \\ \text{on the nature of the input} \end{array} \right.$, it is difficult to give a complexity independent of the input.

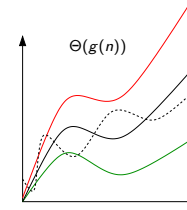
We're interested in execution time **in the worst case** :

- upper bound for any input of the same size,
- for certain algorithms, the worst happens quite often (e.g., if you're looking for information in a database that doesn't contain it),
- the average case is often as bad as the worst case (e.g. insertion sorting).

Simplification of the expression found :

- The real cost of each instruction is neglected,
- We neglect the abstract cost (c_i) of each instruction,
- We're interested in the order of magnitude of the execution time. We retain only the dominant term when n is very large.
- Finally, we neglect the coefficient in front of this term.

Notations

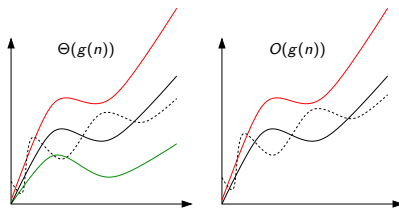


1 Notation $\Theta(g(n))$: Asymptotic Approximate Bound

$$\Theta(g(n)) = \left\{ f(n) \mid \begin{array}{l} \exists c_1 > 0 \\ \exists c_2 > 0 \\ \exists n_0 > 0 \end{array}, \text{ s.t. } \begin{array}{l} 0 \leq c_1 g(n) \leq f(n) \leq c_2 g(n), \\ \forall n \geq n_0 \end{array} \right\}$$

Note that $f(n) = \Theta(g(n))$ for $f \in \Theta(g(n))$.
 « $f(n)$ is equal to $g(n)$ to within one constant factor. »
 $g(n)$ is an **approximate asymptotic bound** for f .

Notations



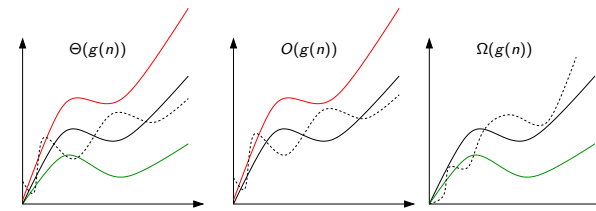
2 Notation $O(g(n))$: Asymptotic Upper Bound

$$O(g(n)) = \left\{ f(n) \mid \begin{array}{l} \exists c > 0 \\ \exists n_0 > 0 \end{array}, \text{ s.t. } \begin{array}{l} 0 \leq f(n) \leq cg(n), \\ \forall n \geq n_0 \end{array} \right\}$$

This is an **upper bound to within one constant**.

- $\Theta(g(n)) \subset O(g(n))$
- $\Theta(n) \subset O(n^2)$. Be careful.

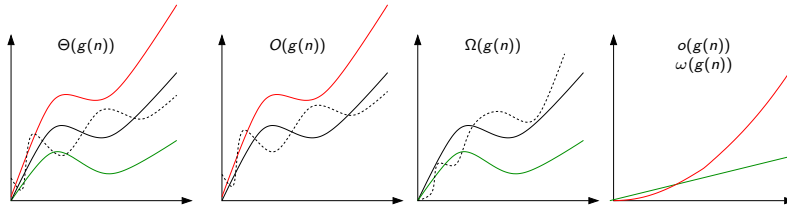
Notations



3 Notation $\Omega(g(n))$: Asymptotic Lower Bound

$$\Omega(g(n)) = \left\{ f(n) \mid \begin{array}{l} \exists c > 0 \\ \exists n_0 > 0 \end{array}, \text{ s.t. } \begin{array}{l} 0 \leq cg(n) \leq f(n), \\ \forall n \geq n_0 \end{array} \right\}$$

This is an **lower bound to within one constant**.



4 Notation $o(g(n))$: non-asymptotically approximated upper bound

$$o(g(n)) = \left\{ f(n) \mid \forall c > 0 \quad \exists n_0 > 0 \quad \text{s.t.} \quad 0 \leq f(n) < cg(n), \quad \forall n \geq n_0 \right\}$$

$f(n)$ becomes negligible in front of $g(n)$ as n tends to $+\infty$. Examples :
For example, $2n = o(n^2)$ and $2n = O(n^2)$.
On the other hand, $2n^2 \neq o(n^2)$ and $2n^2 = O(n^2)$.

5 Notation $\omega(g(n))$: non-asymptotically approximated lower bound

$$f(n) \in \omega(g(n)) \iff g(n) \in o(f(n))$$

Many algorithms have a recursive structure :

- recursive calls to very similar sub-problems,
- these calls separate the problem into several similar subproblems of smaller size.
- they solve the sub-problems recursively
- then combine the solutions of the sub-problems to calculate the solution to the problem.

There are three steps to each level :

- Divide the problem,
- Reign in the sub-problems by solving them recursively,
- Combine sub-problem solutions.

- Divide : divide the array into 2 sub-arrays of approximately same size.
- Reign : sort each of the sub-arrays.
- Combine : merge the two previously sorted sub-arrays.

Remark :

- If $\text{size}(\text{table}) \leq 1$: it's sorted, nothing to do. (basic case)
- Main stage : the **fusion**.

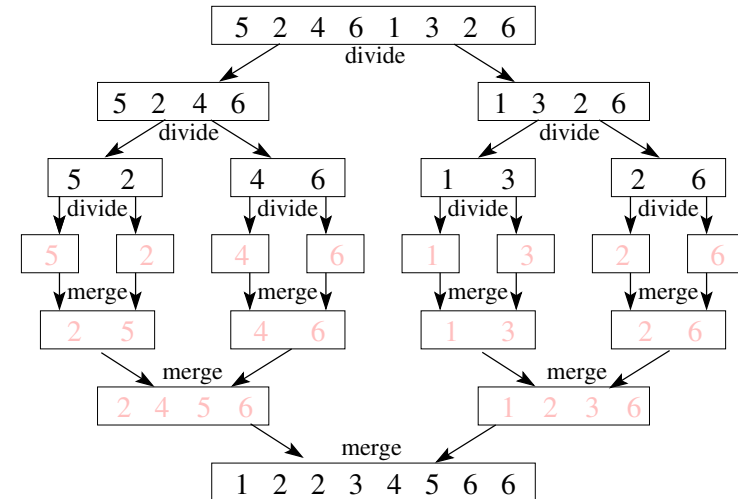
MERGE(A,p,q,r) where A is an array, p,q,r are s.t. $p \leq q < r$.

- $A[p..q]$ and $A[q+1..r]$ are supposed to be sorted.
- it merges them to form $A[p..r]$ sorted.

It's easy to write an algorithm in $\Theta(r - p + 1)$ that performs this fusion (leave as an exercise).

```

1 def Merge_sort (A, p, r):
2   if (p < r) :
3     q = (int) (q+p)/2
4     Merge_sort (A,p,q)
5     Merge_sort (A,q+1,r)
6     MERGE (A,p,q,r)
    
```



Execution time can often be written as a recurrence equation that describes the overall execution time for a problem of size n as a function of the execution time for smaller inputs.

Let $T(n)$ be the execution time for an input of size n .

- If the size is reduced ($n \leq n_0$) : direct solution, calculable in $\Theta(1)$.
- Assume that :
 - we divide the problem into a ss-pb each of size n/b .
 - we need $D(n)$ to divide the problem, and
 - we need $C(n)$ to construct the final solution.

The recurrence is then :

$$T(n) = \begin{cases} \Theta(1) & \text{if } n \leq n_0 \\ aT(n/b) + D(n) + C(n) & \text{otherwise} \end{cases}$$

- Divide : center index calculation : $D(n) = \Theta(1)$
- Merge sort :
 - Reign : $2 \times T(n/2)$
 - Combine : $C(n) = \Theta(n)$

- 1 Substitution method : Only if we have an idea of the solution.
We replace one of the terms in the equation by the solution presented.

$$\begin{aligned} T\left(\frac{n}{2}\right) &\leq c\left(\frac{n}{2}\right)\log_2\left(\frac{n}{2}\right) \\ T(n) &\leq 2T\left(\frac{n}{2}\right) + C(n) = 2\left(c\left(\frac{n}{2}\right)\log_2\left(\frac{n}{2}\right)\right) + kn \\ &\leq cn\log_2\left(\frac{n}{2}\right) + kn \\ &\leq cn\log_2(n) - cn\log_2(2) + kn \quad \text{on } a : \log_2(2) = 1 \\ &\leq cn\log_2(n) - cn + kn \\ &\leq cn\log_2(n) + n(k - c) \end{aligned} \quad (1)$$

We find the solution for n (only if $c > k$).

We must also check that this property is also valid at the limits, i.e. that we can choose c such that $T(n) \leq cn\log_2(n)$ also holds at the limit. There may be a few problems. For $n = 1$ we have :

$$\begin{cases} T(1) = 1 \\ T(1) \leq c \times 1 \times \log_2(1) = 0 \end{cases}$$

The property must therefore be verified for $n \geq n_0$. From the recurrence, we have $T(2) = 5$ and $T(3) = 9$ and we must choose c such that :

$$\begin{cases} 5 = T(2) \leq c \times 2 \times \log_2(2) \\ 9 = T(3) \leq c \times 3 \times \underbrace{\log_2(3)}_{=1.58} \end{cases}$$

$c \geq 2$ is a sufficient condition.

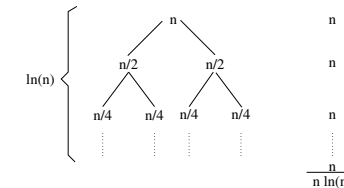
- 2 Iterative method : we iterate the recurrence until we obtain the solution.
To simplify : n is assumed to be a power of 2.

$$\begin{aligned} T(n) &= 2T(n/2) + \underbrace{n}_{\text{fusion}} + \underbrace{1}_{\text{diviser}} \\ &= 2 \left(2T(n/4) + \underbrace{n/2}_{\text{fusion}} + \underbrace{1}_{\text{diviser}} \right) + \underbrace{n}_{\text{fusion}} + \underbrace{1}_{\text{diviser}} \\ &= 4T(n/4) + \underbrace{2/2n + n}_{\text{fusion}} + \underbrace{1 + 2}_{\text{diviser}} \\ &= 2 \left(4T(n/8) + \underbrace{n/4}_{\text{fusion}} + \underbrace{1}_{\text{diviser}} \right) + \underbrace{2/2n + n}_{\text{fusion}} + \underbrace{1 + 2}_{\text{diviser}} \\ &= 8T(n/8) + \underbrace{4/4n + 2/2n + n}_{\text{fusion}} + \underbrace{1 + 2 + 4}_{\text{diviser}} \end{aligned} \quad (1)$$

Iteration leads to $T(1)$ when $n/2^i = 1$, i.e. when $i \geq \log_2(n)$.

$$\begin{aligned} T(n) &= 2^i T(1) + \underbrace{n + 2/2n + 4/4n + \dots + 2^i/2^i n}_{\text{fusion}} + \underbrace{\sum_{i=0}^{k=\log_2(n)-1} 2^i}_{\text{diviser}} \\ &= nT(1) + \underbrace{n\log_2(n)}_{\text{fusion}} + \underbrace{2^{\log_2(n)-1+1} - 1}_{\text{diviser}} \\ &= nT(1) + \underbrace{n\log_2(n)}_{\text{fusion}} + \underbrace{n - 1}_{\text{diviser}} \\ &= O(n \cdot \log_2(n)) \end{aligned} \quad (2)$$

- 2 Iterative method :



A reminder of a remarkable identity :

- $(A^n - B^n) = (A - B)(A^{n-1} + A^{n-2}B + A^{n-3}B^2 + \dots + AB^{n-2} + B^{n-1})$
- $A^n - 1 = (A - 1)(A^{n-1} + A^{n-2} + A^{n-3} + \dots + A + 1)$
- $2^n - 1 = (2 - 1)(2^{n-1} + 2^{n-2} + 2^{n-3} + \dots + 2 + 1)$

A reminder of logarithms

- $\log_a(A)$ is the number x such that $a^x = A$
- \log neperian : $\ln = \log_e$ where $e = 2.718\dots$
- \log decimal : $\text{Log}(x) = \log_{10}(x) = \ln(x)/\ln(10)$
- Properties :

$$\begin{aligned} \ln(ab) &= \ln(a) + \ln(b) & \ln(a/b) &= \ln(a) - \ln(b) \\ \ln(a^b) &= b \ln(a) & \log_b(a) &= \ln(a)/\ln(b) \text{ because } b^x = e^{x \ln(b)} \end{aligned}$$

In fact, I'm looking for x such that $b^x = a$, i.e. such that $e^{x \ln(b)} = a$. Taking the logarithm, we have $x \ln(b) = \ln(a)$.

③ General method :

Theorem

Let $a \geq 1$, $b > 1$, $f(n)$ be a positive function and let $T(n)$ be defined by the recurrence :

$$T(n) = aT(n/b) + f(n)$$

Then $T(n)$ can be asymptotically bounded as follows :

① if $f(n) = O(n^{\log_b a - \epsilon})$ for a constant $\epsilon > 0$ then
 $T(n) = \Theta(n^{\log_b a})$

② if $f(n) = \Theta(n^{\log_b a})$ then
 $T(n) = \Theta(n^{\log_b a} \ln(n))$

③ if $f(n) = \Omega(n^{\log_b a + \epsilon})$ for a constant $\epsilon > 0$ and
 if $af(n/b) \leq cf(n)$ for $c < 1$ and for any n large enough, then
 $T(n) = \Theta(f(n))$

Please note that some possible situations are not covered.

③ General method : **Example of using the theorem**

① $T(n) = 9T(n/3) + n$

② $T(n) = T(\frac{2}{3}n) + 1$

③ $T(n) = 3T(\frac{n}{4}) + n \cdot \ln(n)$

④ $T(n) = 2T(n/2) + n \cdot \ln(n)$

A sorting algorithm **NOT based** on the comparison of its elements :

- Assumption : the array to be sorted is composed only of integers $\in [0, 63]$.

- ① An array of size 64 is created (initialized to 0).
- ② We browse the initial array, and when we find the value k , we update the array $C : C[k]++;$
- ③ The sorted array is then reconstructed.

Complexity : $O(n)$.