Logic for AI
Master 1 IFI

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Session 6

Possibility Theory

Agenda

- Introduction
- Logic and Uncertainty
- Possibility Distribution
- Possibility Measures
- Possibilistic Logic

Introduction

- Uncertainty pervades information and knowledge
- The handling of uncertainty in inference systems has been an issue for a long time in AI
- Logical formalisms have dominated AI for several decades
  - Modal logic
  - Non-monotonic logic
  - Many-valued logic (e.g., fuzzy logic)
- Bayesian networks have become prominent in AI, but...
  - They "deny" the problem of incomplete knowledge
  - The self-duality of probabilities cannot distinguish the lack of belief in a proposition and the belief in its negation

Logic and Uncertainty

- There has been a divorce between logic and probability in the early 20th century
  - Logic as a foundation for Mathematics
  - Probability instrumental to represent statistical data
- Attempts at logical probability have been unsuccessful
  - Degrees of belief cannot be additive and self-dual
  - Deductions lead to incompatible probabilities or, at best, at interval-valued probabilities
- Some theories have emerged to overcome this problem
  - Walley's imprecise probability theory
  - Dempster-Shafer theory of evidence
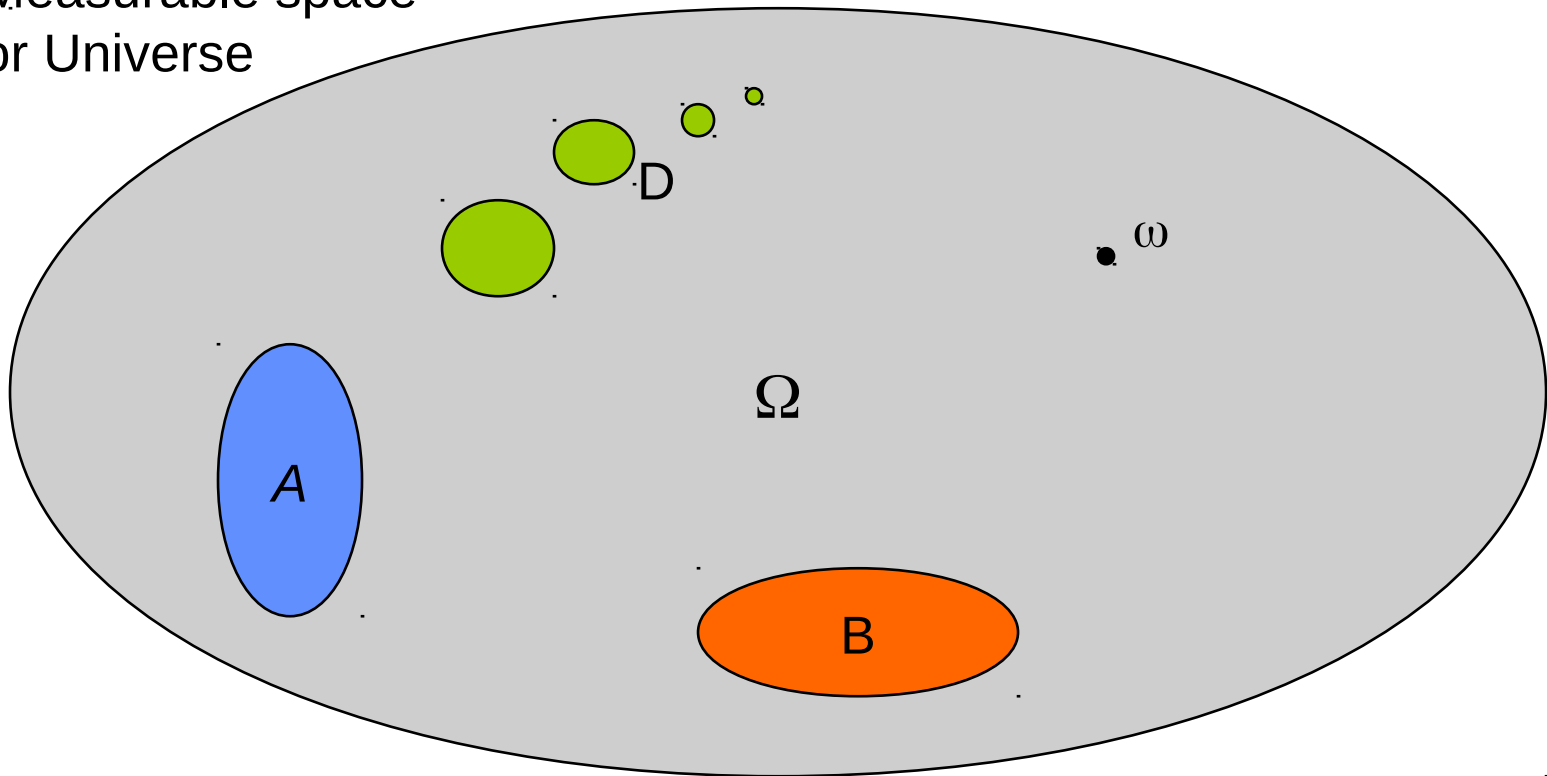 - Possibility theory

Representing Beliefs

When knowledge is incomplete, we may speak of **Beliefs**

There appears to be three traditions for representing beliefs
- Set-Functions
- Multiple-Valued Logic
- Modal Logic

Interpretations / Events

Measurable space
or Universe

Ω

A

B

D

ω

Set Functions

- A set function is used to assign degrees of beliefs to propositions
- A proposition is represented by the set of its models

But Spohn:

$$f : 2^\Omega \to [0, 1] \qquad \kappa : 2^\Omega \to \mathbb{N}$$

$$A \subseteq B \Leftrightarrow f(A) \leq f(B)$$

$$f(\emptyset) = 0$$
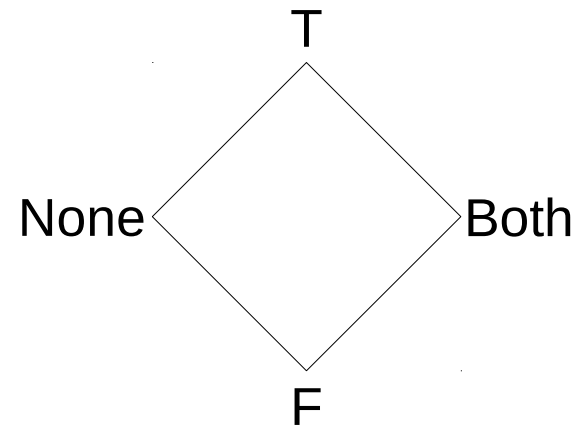
$$f(\Omega) = 1$$

Probability
Possibility and Necessity
Belief and Plausibility
Upper and Lower Probability

Multiple-Valued Logic

- Three-valued logics (Łukasiewicz, Kleene):
    - True
    - False
    - Possible, Unknown, or Indeterminate
- Four-valued logic (Belnap):
    - T, F, Both, None
    - None means unknown
    - Both means conflicting information

Modal Logic

- Represent the belief modality at the syntactic level
- Necessity symbol (modality) $\Box P$
- Clear distinction between $\neg \Box P$ $\Box \neg P$
- Doxastic Logic (von Wright, Hintikka, Fagin *et al.*)
- Axioms:
    - K $\Box(P \Rightarrow Q) \Rightarrow (\Box P \Rightarrow \Box Q)$
    - D $\Box P \Rightarrow \neg \Box \neg P$
    - T $\Box P \Rightarrow P$
    - 4 $\Box P \Rightarrow \Box \Box P$
    - 5 $\neg \Box P \Rightarrow \Box \neg \Box P$

Possibility Distribution

$$\pi : \Omega \to [0, 1]$$

$\pi(\omega) = 0$ Outright impossible

$\pi(\omega) = 1$ Fully possible, not surprising at all

Normalized: $\exists \omega^* \in \Omega : \pi(\omega^*) = 1$

Remark: this is the fuzzy set of possible states of affairs!

Possibility and Necessity Measures

$$\Pi(A) \quad = \quad \max_{\omega \in A} \pi(\omega);$$

$$N(A) \quad = \quad 1 - \Pi(\overline{A}) = \min_{\omega \in \overline{A}} \{1 - \pi(\omega)\}.$$

$$\Pi(\phi) \quad = \quad \max_{\omega \models \phi} \pi(\omega);$$

$$N(\phi) \quad = \quad 1 - \Pi(\neg\phi) = \min_{\omega \not\models \phi} \{1 - \pi(\omega)\}.$$

Properties

Given a **normalized** possibility distribution on a finite universe:

$$\Pi(\bot) = N(\bot) = 0 \qquad\qquad \Pi(\top) = N(\top) = 1$$

$$\Pi(\phi \vee \psi) = \max\{\Pi(\phi), \Pi(\psi)\}$$

$$N(\phi \wedge \psi) = \min\{N(\phi), N(\psi)\}$$

$$\Pi(\phi) = 1 - N(\neg\phi) \qquad\qquad N(\phi) = 1 - \Pi(\neg\phi)$$

$$N(\phi) \leq \Pi(\phi)$$

$$\Pi(\phi) < 1 \Rightarrow N(\phi) = 0 \qquad\qquad N(\phi) > 0 \Rightarrow \Pi(\phi) = 1$$

Possibilistic Logic

$$(\phi, \alpha) \longrightarrow N(\phi) \geq \alpha$$

$$\alpha \in (0, 1]$$

Inference Rules

$(\phi, \alpha) \vdash (\phi, \beta)$ if $\beta \leq \alpha$ (Certainty Weakening)

$(\phi \Rightarrow \psi, \alpha), (\phi, \alpha) \vdash (\psi, \alpha)$ (Modus Ponens)
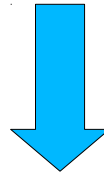
Weakest-Link Resolution

$$(\neg\phi \lor \psi, \alpha), (\phi \lor \xi, \beta) \vdash (\psi \lor \xi, \min\{\alpha, \beta\})$$

Semantics

$$\Sigma = \{(\phi_i, a_i)\}_{i=1,\ldots,n}$$

$$\pi_\Sigma(\omega) = 1 - \max\{a_i : (\phi_i, a_i) \in \Sigma \text{ and } \omega \models \neg\phi_i\}$$

Thank you for your attention